# SELF-AFFINE SETS IN ANALYTIC CURVES AND ALGEBRAIC SURFACES 

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#### Abstract

We characterize analytic curves that contain non-trivial self-affine sets. We also prove that compact algebraic surfaces do not contain non-trivial self-affine sets.


## 1. Introduction

Self-similar and self-affine sets are among the most typical and important fractal objects; see e.g. [2]. They can be generated by the so-called iterated function systems; see Section 2. Although these sets can be very irregular as one expects, they often have very rigid geometric structure.

It is not surprising that typical non-flat smooth manifolds do not contain any non-trivial self-similar or self-affine set. For instance, circles are such examples. To see this, suppose to the contrary that a circle $C$ contains a non-trivial self-affine set $E$. Let $f$ be a contractive affine map in the defining iterated function system of $E$. Then $f(E) \subset E$ and thus $f(E)$ is contained in both $C$ and $f(C)$. However, since $f(C)$ is an ellipse with diameter strictly smaller than that of $C$, the intersection of $f(C)$ and $C$ contains at most two points. This is a contradiction since $f(E)$ is an infinite set.

The above general phenomena was first clarified by Mattila [6] in the self-similar case. He proved that a self-similar set $E$ satisfying the open set condition either lies on an $m$-dimensional affine subspace or $\mathcal{H}^{t}(E \cap M)=0$ for every $m$-dimensional $C^{1}$-submanifold of $\mathbf{R}^{n}$. Here $t$ is the Hausdorff dimension of $E$ and $\mathcal{H}^{t}$ is the $t$ dimensional Hausdorff measure. This result was later generalized to self-conformal sets in $[4,5,7]$. As a related work, Bandt and Kravchenko [1] showed that if $E$ is a self-similar set which spans $\mathbf{R}^{n}$ and $x \in E$, then there does not exist a tangent hyperplane of $E$ at $x$.

As an easy consequence of the result of Mattila or that of Bandt and Kravchenko, an analytic planar curve does not contain any non-trivial self-similar set unless it is a straight line segment. In a private communication, Mattila asked which kind of analytic planar curves can contain a non-trivial self-affine set. The main purpose of this article is to answer this question.

We first remark that any closed parabolic arc is a self-affine set. This interesting fact was first pointed out by Bandt and Kravchenko [1]. In that paper, they considered self-affine planar curves consisting of two pieces $E=f_{1}(E) \cup f_{2}(E)$. They showed that if a certain condition on the eigenvalues of $f_{1}$ and $f_{2}$ holds, then the

[^0]curve $E$ is differentiable at all except for countably many points. They also introduced a stronger condition on the eigenvalues which guarantees the curve $E$ to be continuously differentiable. This result implies that there exist many continuously differentiable self-affine curves. However, Bandt and Kravchenko furthermore showed that self-affine curves cannot be very smooth: the only simple $C^{2}$ self-affine planar curves are parabolic arcs and straight lines.

In our main result, instead of self-affine curves, we consider general self-affine sets and examine when they can be contained in an analytic curve.

Theorem A. An analytic curve in $\mathbf{R}^{n}, n \geq 2$, which cannot be embedded in a hyperplane contains a non-trivial self-affine set if and only if it is an affine image of $\eta:[c, d] \rightarrow \mathbf{R}^{n}, \eta(t)=\left(t, t^{2}, \ldots, t^{n}\right)$, for some $c<d$.

The above result gives a complete answer to the question of Mattila: the only analytic planar curves that contain non-trivial self-affine sets are parabolic arcs and straight line segments. As explained by Mattila, the question is related to the study of singular integrals and self-similar sets in Heisenberg groups. In such groups, selfsimilar sets are self-affine in the Euclidean metric. From the singular integral theory point of view, it is thus important to understand when a self-affine set is contained in an analytic manifold.

Concerning manifolds, we study an analogue of Mattila's question. We examine which kind of algebraic surfaces can contain self-affine sets. Our result shows that this cannot happen on compact surfaces.

Theorem B. A compact algebraic surface does not contain non-trivial self-affine sets.

It is easy to see that non-compact surfaces, such as paraboloids, can contain non-trivial self-affine sets; see Example 4.2. To finish the article, we introduce in Proposition 4.4 a sufficient condition for the inclusion of a self-affine set in an algebraic surface.

## 2. Preliminaries

In this section, we introduce the basic concepts to be used throughout in the article. A mapping $f: \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}$ is affine if $f(x)=T x+c$ for all $x \in \mathbf{R}^{n}$, where $T$ is a $n \times n$ matrix and $c \in \mathbf{R}^{n}$. The matrix $T$ is called the linear part of $f$. It is easy to see that an affine map is invertible if and only if its linear part is non-singular. A mapping $f: \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}$ is strictly contractive if $|f(x)-f(y)|<|x-y|$ for all $x, y \in \mathbf{R}^{n}$. Note that an affine mapping $f$ is strictly contractive if and only if its linear part $T$ has operator norm $\|T\|$ strictly less than 1 . A non-empty compact set $E \subset \mathbf{R}^{n}$ is called self-affine if $E=\bigcup_{i=1}^{\ell} f_{i}(E)$, where $\left\{f_{i}\right\}_{i=1}^{\ell}$ is an affine iterated function system (IFS), i.e. a finite collection of strictly contractive invertible affine maps $f_{i}: \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}$; see [3]. Moreover, $E$ is called self-similar if all the $f_{i}$ 's are similitudes. We say that a self-affine set is non-trivial if it is not a singleton.

If $a<b$, then a non-constant continuous function $\gamma:[a, b] \rightarrow \mathbf{R}^{n}$ is called a curve. We denote the set $\gamma([a, b]) \subset \mathbf{R}^{n}$ by $\operatorname{Img}(\gamma)$ and refer to it also as a curve. By saying that a curve $\gamma$ contains a set $A$ we obviously mean that $A \subset \operatorname{Img}(\gamma)$. A curve $\gamma$ is simple if $\gamma(s) \neq \gamma(t)$ for $a \leq s<t<b$. We say that a curve $\gamma:[a, b] \rightarrow \mathbf{R}^{n}$, $\gamma(t)=\left(x_{1}(t), \ldots, x_{n}(t)\right)$, is analytic if $x_{i}:[a, b] \rightarrow \mathbf{R}$ is continuous on $[a, b]$ and real analytic on $(a, b)$ for all $i \in\{1, \ldots, n\}$. Recall that a function is real analytic on an open set $U \subset \mathbf{R}$ if, at any point $t \in U$, it can be represented by a convergent
power series on some interval of positive radius centered at $t$. Similarly, if $x_{i}$ 's are $C^{k}$ functions for some $k \in \mathbf{N}$, then the curve $\gamma$ is called $C^{k}$ curve. The $k$-th derivative of a $C^{k}$ curve $\gamma$ is $\gamma^{(k)}(t)=\left(x_{1}^{(k)}(t), \ldots, x_{n}^{(k)}(t)\right)$. If $f: \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}$ is an invertible affine mapping and $\gamma:[a, b] \rightarrow \mathbf{R}^{n}$ is a curve, then $f \circ \gamma$ is the affine image of the curve.

Let $P: \mathbf{R}^{n} \rightarrow \mathbf{R}$ be a non-constant polynomial with real coefficients. The set

$$
S(P)=\left\{x \in \mathbf{R}^{n}: P(x)=0\right\}
$$

is called an algebraic surface. The degree of $P$, denoted by $\operatorname{deg}(P)$, is the highest degree of its terms, when $P$ is expressed in canonical form. The degree of a term is the sum of the exponents of the variables that appear in it.

## 3. Self-affine sets and analytic curves

In this section, we prove Theorem A. Our arguments are inspired by the proof of $\left[1\right.$, Theorem 3(i)]. We will first show that an affine image of $\eta:[c, d] \rightarrow \mathbf{R}^{n}$, $\eta(t)=\left(t, t^{2}, \ldots, t^{n}\right)$, contains a non-trivial self-affine set. This follows immediately from the following lemma.

Lemma 3.1. If $\eta:[c, d] \rightarrow \mathbf{R}^{n}$ is given by $\eta(t)=\left(t, t^{2}, \ldots, t^{n}\right)$, then $\operatorname{Img}(\eta)$ is a non-trivial self-affine set for all $c<d$.

Proof. Let

$$
0<\lambda<\left(2^{n} \sqrt{n} \max \left\{(2|c|+1)^{n},(|c|+|d|+1)^{n}\right\}\right)^{-1}<1
$$

and choose $t_{1}, \ldots, t_{\ell} \in[c, d]$ with $\ell \in \mathbf{N}$ such that the self-similar set of $\{x \mapsto$ $\left.\lambda(x-c)+t_{i}\right\}_{i=1}^{\ell}$ is $[c, d]$. Write $c_{i, k, j}=\binom{k}{j}\left(\frac{t_{i}}{\lambda}-c\right)^{k-j}$ and observe that

$$
\left(t-\left(c-\frac{t_{i}}{\lambda}\right)\right)^{k}=\sum_{j=1}^{k} c_{i, k, j}\left(t^{j}-\left(c-\frac{t_{i}}{\lambda}\right)^{j}\right)
$$

for all $k \in\{1, \ldots, n\}, i \in\{1, \ldots, \ell\}$, and $t \in \mathbf{R}$.
Defining for each $i \in\{1, \ldots, \ell\}$ a lower-triangular matrix by

$$
T_{i}=\left(\begin{array}{ccccc}
\lambda c_{i, 1,1} & 0 & 0 & \cdots & 0 \\
\lambda^{2} c_{i, 2,1} & \lambda^{2} c_{i, 2,2} & 0 & \cdots & 0 \\
\lambda^{3} c_{i, 3,1} & \lambda^{3} c_{i, 3,2} & \lambda^{3} c_{i, 3,3} & \cdots & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
\lambda^{n} c_{i, n, 1} & \lambda^{n} c_{i, n, 2} & \lambda^{n} c_{i, n, 3} & \cdots & \lambda^{n} c_{i, n, n}
\end{array}\right)
$$

we see, by the choice of $\lambda$ and the fact that $t_{i} \in[c, d]$, that

$$
\begin{aligned}
\left\|T_{i}\right\| & \leq \sqrt{n} \max _{k \in\{1, \ldots, n\}} \sum_{j=1}^{k}\left|\lambda^{k} c_{i, k, j}\right|=\sqrt{n} \max _{k \in\{1, \ldots, n\}} \sum_{j=1}^{k} \lambda^{k}\binom{k}{j}\left|\frac{t_{i}}{\lambda}-c\right|^{k-j} \\
& \leq \sqrt{n} \max _{k \in\{1, \ldots, n\}} \sum_{j=1}^{k} \lambda^{j}\binom{k}{j}\left(\left|t_{i}\right|+|c|+1\right)^{k-j} \leq \lambda \sqrt{n} \max _{k \in\{1, \ldots, n\}}\left(\left|t_{i}\right|+|c|+1\right)^{k} 2^{k}<1 .
\end{aligned}
$$

Therefore, the affine map $f_{i}: \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}$ defined by

$$
f_{i}\left(x_{1}, \ldots, x_{n}\right)=T_{i}\left(x_{1}, \ldots, x_{n}\right)-T_{i}\left(c-\frac{t_{i}}{\lambda},\left(c-\frac{t_{i}}{\lambda}\right)^{2}, \ldots,\left(c-\frac{t_{i}}{\lambda}\right)^{n}\right)
$$

is contractive and satisfies

$$
\begin{aligned}
f_{i}\left(t, t^{2}, \ldots, t^{n}\right) & =T_{i}\left(t-\left(c-\frac{t_{i}}{\lambda}\right), t^{2}-\left(c-\frac{t_{i}}{\lambda}\right)^{2}, \ldots, t^{n}-\left(c-\frac{t_{i}}{\lambda}\right)^{n}\right) \\
& =\left(\lambda\left(t-\left(c-\frac{t_{i}}{\lambda}\right)\right), \lambda^{2}\left(t-\left(c-\frac{t_{i}}{\lambda}\right)\right)^{2}, \ldots, \lambda^{n}\left(t-\left(c-\frac{t_{i}}{\lambda}\right)\right)^{n}\right) \\
& =\left(\lambda(t-c)+t_{i},\left(\lambda(t-c)+t_{i}\right)^{2}, \ldots,\left(\lambda(t-c)+t_{i}\right)^{n}\right)
\end{aligned}
$$

for all $t \in[c, d]$. Hence the self-affine set of $\left\{f_{i}\right\}_{i=1}^{\ell}$ is the curve $\operatorname{Img}(\eta)$.
Remark 3.2. The key fact implicitly used in the above proof is that $\eta(t)=$ $\left(t, t^{2}, \ldots, t^{n}\right)$ defined on $\mathbf{R}$ is invariant under homotheties $\operatorname{diag}\left(s, s^{2}, \ldots, s^{n}\right)$ and translations $\left(t, t^{2}, \ldots, t^{n}\right) \mapsto\left(t-a,(t-a)^{2}, \ldots,(t-a)^{n}\right)$.

Let us next focus on the opposite claim.
Theorem 3.3. If an analytic curve which cannot be embedded in a hyperplane contains a non-trivial self-affine set, then it is an affine image of $\eta:[c, d] \rightarrow \mathbf{R}^{n}$, $\eta(t)=\left(t, t^{2}, \ldots, t^{n}\right)$, for some $c<d$.

Proof. Let $\gamma:[a, b] \rightarrow \mathbf{R}^{n}$ be an analytic curve such that $\operatorname{Img}(\gamma)$ is not contained in a hyperplane. Suppose that $E$ is a non-trivial self-affine set of an affine IFS $\left\{f_{i}\right\}_{i=1}^{\ell}$ such that $E \subset \operatorname{Img}(\gamma)$. Let $\mathcal{S}$ be the semigroup generated by $f_{1}, \ldots, f_{\ell}$ under composition.

By analyticity and the assumption that $\operatorname{Img}(\gamma)$ is not contained in a hyperplane, without loss of generality, we may assume that $E \subset \gamma((a, b))$ and $\gamma^{\prime}(t) \neq 0$ for all $t \in(a, b)$. Since $(a, b)$ has a countable cover of open intervals $I_{i}$ such that $\gamma\left(I_{i}\right)$ has no intersection points, we have $E \subset \bigcup_{i} E \cap \gamma\left(I_{i}\right)$ and therefore, by the Baire Category Theorem, there exist $i$ and an open set $U$ such that $\emptyset \neq E \cap U \subset E \cap \gamma\left(I_{i}\right)$. Since $E \cap U$ contains a non-trivial self-affine set, we see that no generality is lost if we assume the curve $\gamma$ to be simple.

Fix $\varphi \in \mathcal{S}$ and write

$$
\begin{equation*}
\varphi(x)=M\left(x-x_{0}\right)+x_{0} \tag{3.1}
\end{equation*}
$$

for all $x \in \mathbf{R}^{n}$, where $x_{0} \in \mathbf{R}^{n}$ is the fixed point of $\varphi$ and $M$ is an $n \times n$ invertible matrix. Note that $x_{0} \in E$. Since $E \subset \gamma((a, b))$ there exists $t_{0} \in(a, b)$ such that $x_{0}=\gamma\left(t_{0}\right)$. Hence we may rewrite (3.1) as

$$
\begin{equation*}
\varphi(x)=M\left(x-\gamma\left(t_{0}\right)\right)+\gamma\left(t_{0}\right) . \tag{3.2}
\end{equation*}
$$

Since $E$ is non-trivial, there exists a sequence $\left(t_{i}\right)_{i \in \mathbf{N}}$ of distinct numbers in $(a, b)$ such that $t_{i} \rightarrow t_{0}$ as $i \rightarrow \infty$ and $\gamma\left(t_{i}\right) \in E$ for all $i \in \mathbf{N}$. Furthermore, since $\varphi(E) \subset E \subset \gamma((a, b))$, we see that $\varphi\left(\gamma\left(t_{i}\right)\right) \in \operatorname{Img}(\gamma)$ and therefore, for each $i \in \mathbf{N}$ there exists $t_{i}^{\prime} \in(a, b)$ such that

$$
\begin{equation*}
\varphi\left(\gamma\left(t_{i}\right)\right)=\gamma\left(t_{i}^{\prime}\right) \tag{3.3}
\end{equation*}
$$

Recalling that $\gamma$ is simple and $\varphi\left(\gamma\left(t_{0}\right)\right)=\gamma\left(t_{0}\right)$, we see that $t_{i}^{\prime} \rightarrow t_{0}$ as $i \rightarrow \infty$. By (3.2) and (3.3), we have

$$
\begin{equation*}
M\left(\gamma\left(t_{i}\right)-\gamma\left(t_{0}\right)\right)=\varphi\left(\gamma\left(t_{i}\right)\right)-\gamma\left(t_{0}\right)=\gamma\left(t_{i}^{\prime}\right)-\gamma\left(t_{0}\right) \tag{3.4}
\end{equation*}
$$

and therefore,

$$
M\left(\frac{\gamma\left(t_{i}\right)-\gamma\left(t_{0}\right)}{t_{i}-t_{0}}\right)=\frac{\gamma\left(t_{i}^{\prime}\right)-\gamma\left(t_{0}\right)}{t_{i}^{\prime}-t_{0}} \cdot \frac{t_{i}^{\prime}-t_{0}}{t_{i}-t_{0}} .
$$

Letting $i \rightarrow \infty$, we have

$$
\begin{equation*}
M \gamma^{\prime}\left(t_{0}\right)=\lambda \gamma^{\prime}\left(t_{0}\right), \tag{3.5}
\end{equation*}
$$

where $\lambda=\lim _{i \rightarrow \infty}\left(t_{i}^{\prime}-t_{0}\right) /\left(t_{i}-t_{0}\right) \neq 0$ by the invertibility of $M$.
Let $J$ be an invertible matrix such that

$$
J^{-1} \gamma^{\prime}\left(t_{0}\right)=(1,0, \ldots, 0)
$$

and

$$
J^{-1} M J=\left(\begin{array}{cccc}
A_{1} & 0 & \cdots & 0 \\
0 & A_{2} & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \cdots & A_{m}
\end{array}\right)
$$

is a real canonical Jordan form of $M$. Write $A=J^{-1} M J$ and recall that if $\lambda_{i}$ is a real eigenvalue of $M$, then

$$
A_{i}=\left(\begin{array}{cccccc}
\lambda_{i} & 1 & 0 & \cdots & 0 & 0 \\
0 & \lambda_{i} & 1 & \cdots & 0 & 0 \\
0 & 0 & \lambda_{i} & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & \lambda_{i} & 1 \\
0 & 0 & 0 & \cdots & 0 & \lambda_{i}
\end{array}\right),
$$

and if $\lambda_{i}$ is a non-real eigenvalue of $M$ with real part $a_{i}$ and imaginary part $b_{i}$, then

$$
A_{i}=\left(\begin{array}{cccccc}
C_{i} & I & 0 & \cdots & 0 & 0 \\
0 & C_{i} & I & \cdots & 0 & 0 \\
0 & 0 & C_{i} & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & C_{i} & I \\
0 & 0 & 0 & \cdots & 0 & C_{i}
\end{array}\right)
$$

where

$$
C_{i}=\left(\begin{array}{cc}
a_{i} & b_{i} \\
-b_{i} & a_{i}
\end{array}\right) \quad \text { and } \quad I=\left(\begin{array}{ll}
1 & 0 \\
0 & 1
\end{array}\right) .
$$

Note that by (3.5), we have $\lambda_{1}=\lambda \in \mathbf{R}$. Moreover by (3.4),

$$
\begin{equation*}
A J^{-1}\left(\gamma\left(t_{i}\right)-\gamma\left(t_{0}\right)\right)=J^{-1}\left(\gamma\left(t_{i}^{\prime}\right)-\gamma\left(t_{0}\right)\right) \tag{3.6}
\end{equation*}
$$

for all $i \in \mathbf{N}$.
Defining $\tilde{\gamma}:[a, b] \rightarrow \mathbf{R}^{n}$ by

$$
\begin{equation*}
\tilde{\gamma}(t)=J^{-1}\left(\gamma(t)-\gamma\left(t_{0}\right)\right), \tag{3.7}
\end{equation*}
$$

we clearly have $\tilde{\gamma}\left(t_{0}\right)=0$ and $\tilde{\gamma}^{\prime}\left(t_{0}\right)=J^{-1} \gamma^{\prime}\left(t_{0}\right)=(1,0, \ldots, 0)$. Write $\tilde{\gamma}(t)=$ $\left(\tilde{x}_{1}(t), \ldots, \tilde{x}_{n}(t)\right)$. Then $\tilde{x}_{1}\left(t_{0}\right)=0$ and $\tilde{x}_{1}^{\prime}\left(t_{0}\right)=1 \neq 0$. By the inverse function theorem, the function $\tilde{x}_{1}(t)$ has a local inverse $t=t\left(\tilde{x}_{1}\right)$ which is analytic on $(-\varepsilon, \varepsilon)$ for some $\varepsilon>0$. Write $x_{1}^{*}=\tilde{x}_{1}$ and $x_{k}^{*}\left(x_{1}^{*}\right)=\tilde{x}_{k}\left(t\left(x_{1}^{*}\right)\right)$ for $k \in\{2, \ldots, n\}$. Clearly $x_{k}^{*}(\cdot)$ is analytic on $(-\varepsilon, \varepsilon)$ for all $k \in\{2, \ldots, n\}$. Note that

$$
\begin{equation*}
x_{k}^{*}(0)=\tilde{x}_{k}\left(t_{0}\right)=0, \quad\left(x_{k}^{*}\right)^{\prime}(0)=\tilde{x}_{k}^{\prime}\left(t_{0}\right) \cdot t^{\prime}(0)=0 \tag{3.8}
\end{equation*}
$$

for all $k \in\{2, \ldots, n\}$ and $x_{2}^{*}, \ldots, x_{n}^{*}$ are not constant functions. Indeed, if $x_{k}^{*}$ is constant for some $k$, then so is $\tilde{x}_{k}$; by the fact that each $\tilde{x}_{k}$ is a linear combination of
$x_{1}, \ldots, x_{n}$ (see (3.7)), the curve $\gamma$ would be contained in a hyperplane in $\mathbf{R}^{n}$, leading to a contradiction. Let $\xi:(-\varepsilon, \varepsilon) \rightarrow \mathbf{R}^{n}$ be defined by

$$
\begin{equation*}
\xi\left(x_{1}^{*}\right)=\left(x_{1}^{*}, x_{2}^{*}\left(x_{1}^{*}\right), \ldots, x_{n}^{*}\left(x_{1}^{*}\right)\right) . \tag{3.9}
\end{equation*}
$$

Then $\xi$ is a re-parametrization of the curve $\tilde{\gamma}$ restricted on a neighborhood of $t_{0}$. The goal of the proof is to show that an affine image of the curve $\xi$ will be of the claimed form.

Let us next collect three facts related to the above defined setting.
Fact 1. Write $A=\left(a_{i j}\right)_{1 \leq i, j \leq n}$ and let $Y=a_{11} x_{1}^{*}+\sum_{j=2}^{n} a_{1 j} x_{j}^{*}\left(x_{1}^{*}\right)$. Then

$$
\begin{equation*}
A\left(x_{1}^{*}, x_{2}^{*}\left(x_{1}^{*}\right), \ldots, x_{n}^{*}\left(x_{1}^{*}\right)\right)=\left(Y, x_{2}^{*}(Y), \ldots, x_{n}^{*}(Y)\right) \tag{3.10}
\end{equation*}
$$

for all $x_{1}^{*} \in(-\varepsilon, \varepsilon)$.
Proof. By (3.6), $A \tilde{\gamma}\left(t_{i}\right)=\tilde{\gamma}\left(t_{i}^{\prime}\right)$ for all $i \in \mathbf{N}$. Hence the equality (3.10) holds for infinitely many different values of $x_{1}^{*}$ in a small closed neighborhood of 0 . By analyticity, (3.10) holds on the whole interval $(-\varepsilon, \varepsilon)$.

The next fact concerns the shape of the matrix $A$.
Fact 2. The matrix $A$ is diagonal. In other words, all the block matrices $A_{i}$ have dimension 1.

Proof. Let us first show that $A_{1}$ has dimension 1. Suppose to the contrary that $d_{1}=\operatorname{dim}\left(A_{1}\right)>1$. Since the eigenvalue associated to $A_{1}$ is $\lambda \in \mathbf{R}$, we have

$$
A_{1}=\left(\begin{array}{ccccc}
\lambda & 1 & \cdots & 0 & 0 \\
0 & \lambda & \cdots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \cdots & \lambda & 1 \\
0 & 0 & \cdots & 0 & \lambda
\end{array}\right)
$$

By Fact 1, we see that

$$
\begin{equation*}
\lambda x_{d_{1}}^{*}\left(x_{1}^{*}\right)=x_{d_{1}}^{*}\left(\lambda x_{1}^{*}+x_{2}^{*}\left(x_{1}^{*}\right)\right) . \tag{3.11}
\end{equation*}
$$

By (3.8) and the fact that $x_{k}^{*}, k \in\{2, \ldots, n\}$, is not a constant, there exist integers $p_{2}, \ldots, p_{n} \geq 2$ and reals $c_{2}, \ldots, c_{n} \neq 0$ such that for each $k \in\{2, \ldots, n\}$

$$
\begin{equation*}
x_{k}^{*}\left(x_{1}^{*}\right)=c_{k}\left(x_{1}^{*}\right)^{p_{k}}+o\left(x_{1}^{*}\right)^{p_{k}} \tag{3.12}
\end{equation*}
$$

as $x_{1}^{*} \rightarrow 0$. Plugging (3.12) into (3.11), and comparing the coefficients of Taylor series in $x_{1}^{*}$ on both sides, we get

$$
\lambda c_{d_{1}}=c_{d_{1}} \lambda^{p_{d_{1}}}
$$

which implies that $p_{d_{1}}=1$, a contradiction. Hence we have $\operatorname{dim}\left(A_{1}\right)=1$ and therefore $Y=\lambda x_{1}^{*}$.

Let us next assume inductively that for some $k \in\{1, \ldots, n-1\}$ the matrices $A_{1}, \ldots, A_{k}$ are of dimension 1 and show that $\operatorname{dim}\left(A_{k+1}\right)=1$. Suppose to the contrary that $d=\operatorname{dim}\left(A_{k+1}\right)>1$. Now there are two cases: either $\lambda_{k+1}$ is real or not. First suppose that $\lambda_{k+1}$ is real. Let $\ell=k+d$. By (3.10) we have

$$
\begin{align*}
\lambda_{k+1} x_{\ell-1}^{*}\left(x_{1}^{*}\right)+x_{\ell}^{*}\left(x_{1}^{*}\right) & =x_{\ell-1}^{*}\left(\lambda x_{1}^{*}\right),  \tag{3.13}\\
\lambda_{k+1} x_{\ell}^{*}\left(x_{1}^{*}\right) & =x_{\ell}^{*}\left(\lambda x_{1}^{*}\right) . \tag{3.14}
\end{align*}
$$

Plugging (3.12) into (3.14), and comparing the coefficients of Taylor series in $x_{1}^{*}$ on both sides, we get $\lambda_{k+1}=\lambda^{p_{\ell}}$. Then plug (3.12) into (3.13) to obtain

$$
\lambda^{p_{\ell}} c_{\ell-1}\left(x_{1}^{*}\right)^{p_{\ell-1}}+c_{\ell}\left(x_{1}^{*}\right)^{p_{\ell}}=\lambda^{p_{\ell-1}} c_{\ell-1}\left(x_{1}^{*}\right)^{p_{\ell-1}}+o\left(\left(x_{1}^{*}\right)^{p_{\ell-1}}+\left(x_{1}^{*}\right)^{p_{\ell}}\right)
$$

as $x_{1}^{*} \rightarrow 0$. That is,

$$
\begin{equation*}
\left(\lambda^{p_{\ell}}-\lambda^{p_{\ell-1}}\right) c_{\ell-1}\left(x_{1}^{*}\right)^{p_{\ell-1}}+c_{\ell}\left(x_{1}^{*}\right)^{p_{\ell}}=o\left(\left(x_{1}^{*}\right)^{p_{\ell-1}}+\left(x_{1}^{*}\right)^{p_{\ell}}\right) \tag{3.15}
\end{equation*}
$$

as $x_{1}^{*} \rightarrow 0$. Since $0<|\lambda|<1$ and $c_{\ell-1}, c_{\ell} \neq 0$, one easily derives a contradiction from (3.15) by considering the cases $p_{\ell}<p_{\ell-1}, p_{\ell}=p_{\ell-1}$, and $p_{\ell}>p_{\ell-1}$ separately.

Hence we may assume that $\lambda_{k+1}=a+i b$ with $b \neq 0$. The matrix $A_{k+1}$ is therefore of the form

$$
A_{k+1}=\left(\begin{array}{ccccccc}
a & b & 1 & 0 & \cdots & 0 & 0 \\
-b & a & 0 & 1 & \cdots & 0 & 0 \\
0 & 0 & a & b & \cdots & 0 & 0 \\
0 & 0 & -b & a & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & 0 & \cdots & a & b \\
0 & 0 & 0 & 0 & \cdots & -b & a
\end{array}\right) .
$$

Again let $\ell=k+d$. Applying (3.10), we see that

$$
\begin{aligned}
a x_{\ell-1}^{*}\left(x_{1}^{*}\right)+b x_{\ell}^{*}\left(x_{1}^{*}\right) & =x_{\ell-1}^{*}\left(\lambda x_{1}^{*}\right), \\
-b x_{\ell-1}^{*}\left(x_{1}^{*}\right)+a x_{\ell}^{*}\left(x_{1}^{*}\right) & =x_{\ell}^{*}\left(\lambda x_{1}^{*}\right) .
\end{aligned}
$$

Using the above identities and comparing the coefficients of $\left(x_{1}^{*}\right)^{p_{\ell}}$ and $\left(x_{1}^{*}\right)^{p_{\ell-1}}$ in the Taylor expansions of $x_{\ell}^{*}$ and $x_{\ell-1}^{*}$, we see that $p_{\ell}=p_{\ell-1}$; and moreover,

$$
\begin{aligned}
a c_{\ell-1}+b c_{\ell} & =c_{\ell-1} \lambda^{p_{\ell}}, \\
-b c_{\ell-1}+a c_{\ell} & =c_{\ell} \lambda^{p_{\ell}},
\end{aligned}
$$

or, equivalently,

$$
\left(\begin{array}{cc}
a & b \\
-b & a
\end{array}\right)\binom{c_{\ell-1}}{c_{\ell}}=\lambda^{p_{\ell}}\binom{c_{\ell-1}}{c_{\ell}} .
$$

This means that the real number $\lambda^{p_{\ell}}$ is an eigenvalue of the above matrix, a contradiction.

By Fact 2, we may now write

$$
\begin{equation*}
A=\operatorname{diag}\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{n}\right), \tag{3.16}
\end{equation*}
$$

where $\lambda_{1}=\lambda \in(-1,1) \backslash\{0\}$. With this observation, we can examine how the curve $\xi$ defined in (3.9) looks like.

Fact 3. There exist integers $2 \leq p_{2}<p_{3}<\cdots<p_{n}$ such that a piece of the curve $\operatorname{Img}(\gamma)$, namely $\gamma:\left(t_{0}-\delta_{1}, t_{0}+\delta_{2}\right) \rightarrow \mathbf{R}^{n}$ for some $\delta_{1}, \delta_{2}>0$, is an affine image of the curve $\eta:(-\varepsilon, \varepsilon) \rightarrow \mathbf{R}^{n}$ defined by

$$
\eta(t)=\left(t, t^{p_{2}}, \ldots, t^{p_{n}}\right) .
$$

More precisely, there exists an invertible $n \times n$ matrix $B$ such that the above defined $\eta$ is the re-parametrization of the curve $B\left(\gamma(t)-\gamma\left(t_{0}\right)\right), t \in\left(t_{0}-\delta_{1}, t_{0}+\delta_{2}\right)$.

Proof. We first examine the curve $\xi$ defined in (3.9). By (3.16) and (3.10), we have for $2 \leq k \leq n$,

$$
\begin{equation*}
x_{k}^{*}\left(\lambda x_{1}^{*}\right)=\lambda_{k} x_{k}^{*}\left(x_{1}^{*}\right) \tag{3.17}
\end{equation*}
$$

and hence, by (3.12), there exist integers $p_{2}, \ldots, p_{n} \geq 2$ and reals $c_{2}, \ldots, c_{n} \neq 0$ such that

$$
c_{k}\left(\lambda x_{1}^{*}\right)^{p_{k}}=\lambda_{k} c_{k}\left(x_{1}^{*}\right)^{p_{k}}+o\left(\left(x_{1}^{*}\right)^{p_{k}}\right) .
$$

This implies that $\lambda_{k}=\lambda^{p_{k}}$ and thus $x_{k}^{*}\left(\lambda x_{1}^{*}\right)=\lambda^{p_{k}} x_{k}^{*}\left(x_{1}^{*}\right)$. Taking $p_{k}$-th derivative on both sides gives $\left(x_{k}^{*}\right)^{\left(p_{k}\right)}\left(\lambda x_{1}^{*}\right)=\left(x_{k}^{*}\right)^{\left(p_{k}\right)}\left(x_{1}^{*}\right)$. Hence $\left(x_{k}^{*}\right)^{\left(p_{k}\right)}\left(\lambda^{j} x_{1}^{*}\right)=\left(x_{k}^{*}\right)^{\left(p_{k}\right)}\left(x_{1}^{*}\right)$ for all $j \in \mathbf{N}$. Letting $j \rightarrow \infty$, we get $\left(x_{k}^{*}\right)^{\left(p_{k}\right)}\left(x_{1}^{*}\right) \equiv\left(x_{k}^{*}\right)^{\left(p_{k}\right)}(0)=c_{k} p_{k}$ !. Combining this with (3.12) yields

$$
x_{k}^{*}\left(x_{1}^{*}\right)=c_{k}\left(x_{1}^{*}\right)^{p_{k}} .
$$

Since the curve $\tilde{\gamma}$ is not contained in a hyperplane, we see that, for any nonzero vector $\left(b_{1}, \ldots, b_{n}\right)$, the sum $\sum_{k=1}^{n} b_{k} x_{k}^{*}$ is not identically zero. Thus the integers $p_{2}, \ldots, p_{n}$ are mutually distinct. Hence the curve $\xi:(-\epsilon, \epsilon) \rightarrow \mathbf{R}^{n}$ is of the form $\xi\left(x_{1}^{*}\right)=\left(x_{1}^{*}, c_{2}\left(x_{1}^{*}\right)^{p_{2}}, \ldots, c_{n}\left(x_{1}^{*}\right)^{p_{n}}\right)$. Without confusion, we simply write $\xi(t)=\left(t, c_{2} t^{p_{2}}, \ldots, c_{n} t^{p_{n}}\right)$.

We have now proved that, possibly after a permutation on coordinate axis, the curve $\tilde{\gamma}:\left(t_{0}-\delta_{1}, t_{0}+\delta_{2}\right) \rightarrow \mathbf{R}^{n}$ for some $\delta_{1}, \delta_{2}>0$, can be re-pararemtrized by

$$
t \mapsto\left(t, c_{2} t^{p_{2}}, \ldots, c_{n} t^{p_{n}}\right), t \in(-\epsilon, \epsilon)
$$

for some integers $2 \leq p_{2}<p_{3}<\cdots<p_{n}$ and reals $c_{2}, \ldots, c_{n} \neq 0$. Applying a further affine transformation $\left(u_{1}, u_{2}, \ldots, u_{n}\right) \mapsto\left(u_{1}, u_{2} / c_{2}, \ldots, u_{n} / c_{n}\right)$, we see that $\gamma:\left(t_{0}-\delta_{1}, t_{0}+\delta_{2}\right) \rightarrow \mathbf{R}^{n}$, for some $\delta_{1}, \delta_{2}>0$, is an affine image of the curve $\eta$. This completes the proof of Fact 3 .

By Fact 3, it suffices to show that $p_{k}=k$ for all $k \in\{2, \ldots, n\}$. Observe that $\eta:(-\varepsilon, \varepsilon) \rightarrow \mathbf{R}^{n}$ given by Fact 3 is an analytic simple curve which cannot be embedded in a hyperplane and it contains a non-trivial self-affine set, say $F$. Then there exists $t_{1} \in(-\varepsilon, \varepsilon) \backslash\{0\}$ such that $\eta\left(t_{1}\right)$ is the fixed point of a mapping of the affine IFS defining $F$. Therefore, applying the previous argument (Fact 3) once more (in which $\gamma$ is replaced by $\eta$ ), we find integers $2 \leq q_{2}<q_{3}<\cdots<q_{n}$ and an interval $\left(t_{1}-\delta_{1}^{\prime}, t_{1}+\delta_{2}^{\prime}\right) \subset(-\epsilon, \epsilon)$ for some some $\delta_{1}^{\prime}, \delta_{2}^{\prime}>0$ such that, under a suitable invertible linear transformation $B^{\prime}$, the curve

$$
t \mapsto B^{\prime}\left(\eta(t)-\eta\left(t_{1}\right)\right)
$$

defined on ( $t_{1}-\delta_{1}^{\prime}, t_{1}+\delta_{2}^{\prime}$ ) can be re-parametrized by

$$
t \mapsto\left(t, t^{q_{2}}, \ldots, t^{q_{n}}\right) .
$$

This means that, writing $B^{\prime}=\left(b_{k j}\right)_{1 \leq k, j \leq n}$, we have

$$
\begin{equation*}
\sum_{j=1}^{n} b_{k j}\left(t^{p_{j}}-t_{1}^{p_{j}}\right)=\left(\sum_{j=1}^{n} b_{1 j}\left(t^{p_{j}}-t_{1}^{p_{j}}\right)\right)^{q_{k}} \tag{3.18}
\end{equation*}
$$

for all $t \in\left(t_{1}-\delta_{1}^{\prime}, t_{1}+\delta_{2}^{\prime}\right)$ and $k \in\{2, \ldots, n\}$, where $p_{1}=1$. By analyticity, (3.18) holds for all $t \in \mathbf{R}$.

We will next compare the degrees of polynomials of $t$ on both sides of (3.18) for all $k \in\{2, \ldots, n\}$. Let $d=\operatorname{deg}\left(\sum_{j=1}^{n} b_{1 j}\left(t^{p_{j}}-t_{1}^{p_{j}}\right)\right) \in\left\{1, p_{2}, \ldots, p_{n}\right\}$. When $k$ runs over $\{2, \ldots, n\}$, the degrees of the right-hand side of (3.18) are $d q_{2}, d q_{3}, \ldots, d q_{n}$, whereas the left-hand side has degree in $\left\{1, p_{2}, \ldots, p_{n}\right\}$. Therefore,

$$
\left\{d q_{2}, d q_{3}, \ldots, d q_{n}\right\} \subset\left\{1, p_{2}, \ldots, p_{n}\right\}
$$

which implies that

$$
\begin{equation*}
p_{k}=d q_{k} \tag{3.19}
\end{equation*}
$$

for all $k \in\{2, \ldots, n\}$. Since $d \in\left\{1, p_{2}, \ldots, p_{n}\right\}$, we must have $d=1$ (otherwise, by (3.19), $q_{k}=1$ for some $k \in\{2, \ldots, n\}$ which is a contradiction). But since $d=1$, we may write (3.18) as

$$
\sum_{j=1}^{n} b_{k j}\left(t^{p_{j}}-t_{1}^{p_{j}}\right)=\left(c\left(t-t_{1}\right)\right)^{p_{k}}
$$

for all $k \in\{2, \ldots, n\}$. In particular, this shows that $\left(t-t_{1}\right)^{p_{n}}$ is a linear combination of $\left(t-t_{1}\right),\left(t^{p_{2}}-t_{1}^{p_{2}}\right), \ldots,\left(t^{p_{n}}-t_{1}^{p_{n}}\right)$. Since $t_{1} \neq 0$, all powers $t^{j}, j \in\left\{1, \ldots, p_{n}\right\}$, appear in $\left(t-t_{1}\right)^{p_{n}}$ with non-degenerate coefficients, and it follows that $p_{k}=k$ for all $k \in\{2, \ldots, n\}$.

Remark 3.4. (1) Bandt and Kravchenko showed that there are plenty of $C^{1}$ planar self-affine curves (i.e. self-affine sets that are $C^{1}$ planar curves); see [1, Theorem 2]. Furthermore, in [1, Theorem 3(ii)], they showed that parabolic arcs and straight line segments are the only simple $C^{2}$ planar self-affine curves. This result also follows from Theorem A by a simple modification. It would be interesting to know that if a self-affine set $E$ is contained in a $C^{2}$ planar curve, then does there exists an analytic curve containing $E$ ?
(2) The analyticity assumption in Theorem A is well motivated since for each $k \in \mathbf{N}$ it is easy to construct a non-parabolic $C^{k}$ planar curve containing a self-affine set. To see this, start from a piece of parabolic curve and change a small part of it so that the new curve is $C^{k}$. Clearly the obtained curve still contains a self-affine set. Due to this, it would be interesting to know if there exists a self-affine set $E$ which is a subset of a strictly convex $C^{2}$ planar curve, but is not a subset of any parabolic curve. Also, when can a self-affine set intersect an analytic curve in a set of positive measure for some relevant measure such as the self-affine measure? In the self-conformal case, this property implies that the whole set is contained in an analytic curve; see [4, Theorem 2.1].

## 4. Self-affine sets and algebraic surfaces

In this section, we prove Theorem B and introduce self-affine polynomials.
Proof of Theorem B. Let $P: \mathbf{R}^{n} \rightarrow \mathbf{R}$ be a non-constant polynomial with real coefficients such that $S(P)$ is compact. Suppose to the contrary that there exists a non-trivial self-affine set $E$ contained in $S(P)$. Let $f$ be one of the mappings of the affine IFS defining $E$ and set $P_{j}=P \circ f^{-j}$ for all $j \in \mathbf{N}$. Observe that the degree of $P_{j}$ is at $\operatorname{most} \operatorname{deg}(P)$. It is easy to see that $S\left(P_{j}\right)=f^{j}(S(P))$ for all $j \in \mathbf{N}$ and therefore $\operatorname{diam}\left(S\left(P_{j}\right)\right) \rightarrow 0$ as $j \rightarrow \infty$. By the assumption, we have $f^{j}(E) \subset f^{j}(S(P))=S\left(P_{j}\right)$ for all $j \in \mathbf{N}$, and by the invariance, we have $f^{j}(E) \subset f^{j-1}(E) \subset \cdots \subset E$ for all $j \in \mathbf{N}$.

Since the ring of polynomials having degree at $\operatorname{most} \operatorname{deg}(P)$ is finite dimensional there exist $P_{k_{1}}, \ldots, P_{k_{m}}$ such that each $P_{j}$ is a linear combination of these polynomials. Choose $j$ so large that

$$
\operatorname{diam}\left(S\left(P_{j}\right)\right)<\min _{i \in\{1, \ldots, m\}} \operatorname{diam}\left(f^{k_{i}}(E)\right)=\operatorname{diam}\left(\bigcap_{i=1}^{m} f^{k_{i}}(E)\right)
$$

But since $P_{j}=\sum_{i=1}^{m} c_{i} P_{k_{i}}$ for some $c_{i}$, we have

$$
\bigcap_{i=1}^{m} f^{k_{i}}(E) \subset \bigcap_{i=1}^{m} S\left(P_{k_{i}}\right) \subset S\left(P_{j}\right)
$$

This contradiction finishes the proof.
Remark 4.1. By slightly modifying the above argument, we can prove the following stronger result: If $S(P)$ is an algebraic surface and there exists a contractive affine map $f$ such that $S(P)$ contains the fixed point $z$ of $f$ and a non-periodic orbit $\left\{f^{n}(x)\right\}$ for some $x$, then $S(P)$ is unbounded. To see this, choose $k_{1}<\ldots<k_{m}$ so that each $P_{n}$ is a linear combination of the polynomials $P_{k_{1}}, \ldots, P_{k_{m}}$. If $S(P)$ is bounded, then we can pick $j$ large enough so that $\operatorname{diam}\left(S\left(P_{j}\right)\right)<\left|z-f^{k_{m}}(x)\right|$. This is a contradiction since $S\left(P_{j}\right) \supset \bigcap_{i=1}^{m} S\left(P_{k_{i}}\right) \supset\left\{z, f^{k_{m}}(x)\right\}$.

Example 4.2. It is clear that a hyperplane can contain a non-trivial self-affine set. In this example, we show that also other kinds of non-compact algebraic surfaces can have this property. Let $P: \mathbf{R}^{n} \rightarrow \mathbf{R}, P\left(x_{1}, \ldots, x_{n}\right)=x_{1}^{2}+\cdots+x_{n-1}^{2}-x_{n}$, and observe that, by Lemma 3.1, the parabola $\left\{\left(x_{1}, \ldots, x_{n}\right) \in \mathbf{R}^{n}: x_{n}=x_{1}^{2}\right.$ and $x_{2}=$ $\left.\cdots=x_{n-1}=0\right\} \subset S(P)$ contains non-trivial self-affine sets. It is also easy to see that $S(P)$ contains self-affine sets having dimension larger than one. Fix an interval $[a, b] \subset \mathbf{R}$ and define a mapping $\eta:[a, b]^{n-1} \rightarrow \mathbf{R}^{n}$ by setting $\eta\left(x_{1}, \ldots, x_{n-1}\right)=$ $\left(x_{1}, \ldots, x_{n-1}, x_{1}^{2}+\cdots+x_{n-1}^{2}\right)$. Let $\left\{c_{i}\left(x_{1}, \ldots, x_{n-1}\right)+\left(d_{i}, \ldots, d_{i}\right)\right\}_{i=1}^{\ell}$ be an affine IFS on $\mathbf{R}^{n-1}$ so that $[a, b]^{n-1}$ is the self-affine set generated by it. Define $f_{i}: \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}$ by setting

$$
f_{i}\left(x_{1}, \ldots, x_{n}\right)=\left(\begin{array}{ccccc}
c_{i} & 0 & \cdots & 0 & 0 \\
0 & c_{i} & \cdots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \cdots & c_{i} & 0 \\
2 c_{i} d_{i} & 2 c_{i} d_{i} & \cdots & 2 c_{i} d_{i} & c_{i}^{2}
\end{array}\right)\left(\begin{array}{c}
x_{1} \\
x_{2} \\
\vdots \\
x_{n-1} \\
x_{n}
\end{array}\right)+\left(\begin{array}{c}
d_{i} \\
d_{i} \\
\vdots \\
d_{i} \\
(d-1) d_{i}^{2}
\end{array}\right)
$$

for all $\left(x_{1}, \ldots, x_{n}\right) \in \mathbf{R}^{n}$ and $i \in\{1, \ldots, \ell\}$. Since $f_{i}\left(\eta\left(x_{1}, \ldots, x_{n-1}\right)\right)=\eta\left(c_{i} x_{1}+\right.$ $\left.d_{i}, \ldots, c_{i} x_{d-1}+d_{i}\right)$ the image $\eta\left([a, b]^{n-1}\right) \subset S(P)$ is invariant under the affine IFS $\left\{f_{i}\right\}_{i=1}^{\ell}$.

We shall next introduce a general condition which guarantees the algebraic surface to contain self-affine sets. Suppose that $P: \mathbf{R}^{n} \rightarrow \mathbf{R}$ is a non-constant polynomial with real coefficients. We say that a contractive invertible affine map $f$ is a scaling factor for $P$ if there exists a constant $C \in \mathbf{R}$ such that

$$
\begin{equation*}
P \circ f=C P \tag{4.1}
\end{equation*}
$$

A polynomial $P$ is called self-affine if it has two scaling factors with distinct fixed points.

Example 4.3. Let $P: \mathbf{R}^{2} \rightarrow \mathbf{R}, P\left(x_{1}, x_{2}\right)=x_{2}-x_{1}$. It is easy to see that $f: \mathbf{R}^{2} \rightarrow \mathbf{R}^{2}, f\left(x_{1}, x_{2}\right)=\frac{1}{2}\left(x_{1}, x_{2}\right)$, and $g: \mathbf{R}^{2} \rightarrow \mathbf{R}^{2}, g\left(x_{1}, x_{2}\right)=\frac{1}{2}\left(x_{1}+1, x_{2}+1\right)$, are scaling factors for $P$ and have distinct fixed points.

The following proposition shows that a polynomial $P$ being self-affine is sufficient for the inclusion of self-affine sets.

Proposition 4.4. If $P: \mathbf{R}^{n} \rightarrow \mathbf{R}$ is a self-affine polynomial, then $S(P)$ contains a non-trivial self-affine set.

Proof. Let $f$ be a scaling factor for $P$ with a constant $C$. Note that there exists a non-singular $d \times d$ matrix $M$ with $\|M\|<1$ and $a \in \mathbf{R}^{n}$ so that $f(x)=M x+a$
for all $x \in \mathbf{R}^{n}$. Observe that

$$
f^{j}(x)=M^{j} x+\sum_{i=0}^{j-1} M^{i} a \rightarrow \sum_{i=0}^{\infty} M^{i} a=: x_{0}
$$

as $j \rightarrow \infty$, where $x_{0} \in \mathbf{R}^{n}$ is the fixed point of $f$. Choose $x \in \mathbf{R}^{n}$ such that

$$
\left|P\left(x_{0}\right)\right|+1<|P(x)| .
$$

Such a point $x$ exists since $P$ is not bounded. Since

$$
C^{j} P(x)=P \circ f^{j}(x) \rightarrow P\left(x_{0}\right)
$$

as $j \rightarrow \infty$ we may choose $j$ large enough so that $\left|C^{j} P(x)\right|<\left|P\left(x_{0}\right)\right|+1$. Thus $|C|<1$.

Let $h$ and $g$ be scaling factors for $P$ with distinct fixed points. If $f$ is any finite composition of the mappings $h$ and $g$, then $f$ is a scaling factor for $P$. If $C$ is the constant associated to the scaling factor $f$, then the above reasoning implies that $|C|<1$. Furthermore, if $x_{0}$ is the fixed point of $f$, then $P\left(x_{0}\right)=P \circ f\left(x_{0}\right)=C P\left(x_{0}\right)$. Since $|C|<1$, this implies $P\left(x_{0}\right)=0$ and $x_{0} \in S(P)$. Recalling that $S(P)$ is closed it thus contains the self-affine set generated by the affine IFS $\{h, g\}$.

Remark 4.5. It would be interesting to characterize all the algebraic surfaces associated to self-affine polynomials. For example, in the two-dimensional case, is the surface always contained in a line through the origin? Of course, the ultimate open question here is to characterize all the algebraic surfaces containing self-affine sets.

Acknowledgement. Feng was partially supported by the HKRGC GRF grants (projects CUHK401013, CUHK14302415). The authors are grateful to Christoph Bandt for many valuable comments to improve the paper.

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[^0]:    https://doi.org/10.5186/aasfm.2018.4306
    2010 Mathematics Subject Classification: Primary 28A80; Secondary 32C25, 51H30.
    Key words: Self-affine set, analytic curve, algebraic surface.

