

ON THE SMOOTHNESS OF QUASIHYPHERBOLIC BALLS

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Abstract. We investigate properties of quasihyperbolic balls and geodesics in Euclidean and Banach spaces. Our main result is that in uniformly smooth Banach spaces a quasihyperbolic ball of a convex domain is C^1 -smooth. The question about the smoothness of quasihyperbolic balls is old, originating back to the discussions of Gehring and Vuorinen in 1970's. To our belief, the result is new also in the Euclidean setting. We also address some other issues involving the smoothness of quasihyperbolic balls. We introduce an interesting application of quasihyperbolic metrics to equivalent renormings of Banach spaces. Several examples and illustrations are provided.

1. Introduction

The *quasihyperbolic metric* in \mathbf{R}^n is a natural generalization of the hyperbolic metric, introduced by Gehring [7, 8] and his students Palka and Osgood in 1970's as a tool for studying quasiconformal mappings. Since its introduction, this metric has found numerous applications in the geometric function theory [10, 21]. Furthermore, quasihyperbolic metric can be studied in more general settings than \mathbf{R}^n , such as Banach spaces and even in general metric spaces. It has particular significance in the infinite dimensional settings, where many traditional tools, such as the conformal modulus, cannot be used. This approach to geometric function theory was developed by Väisälä in a series of papers. This theory is called “the free quasiworld” according to Väisälä (see [19], and references therein). Introductory discussion and motivations for the study of this topic are presented in detail in the survey article [13].

In this paper, we continue our investigation of the properties of this metric in Euclidean and Banach spaces, see [11, 12, 16, 17]. We will settle a long-standing problem of whether quasihyperbolic balls of a convex domain on a uniformly smooth Banach space are smooth (see Remark 2.9). Our smoothness considerations yield as a byproduct a new renorming technique of Banach spaces as well. In fact, it turns out that the quasihyperbolic metric is differentiable in a large dense set of points if the Banach space in question satisfies some modest regularity assumptions, e.g., it is separable or has a separable dual, see Theorem 2.4. This approach is made possible by the fact that the underlying Banach space geometry is conveyed to the geometric properties of the quasihyperbolic metric. Thus we have access to the functional analysis machinery in studying the properties of the quasihyperbolic metric. This includes topics such as the convexity of balls and smoothness of geodesics, and an approach to analyzing these matters was developed in our earlier papers [16, 17].

<https://doi.org/10.5186/aasfm.2017.4226>

2010 Mathematics Subject Classification: Primary 58B10, 30C65; Secondary 46T05, 46B03.

Key words: Quasihyperbolic metric, geodesics, uniqueness, smoothness, convexity, renorming.

The smoothness of quasihyperbolic balls has been investigated in [14] in the setting of Hilbert spaces.

This paper is organized as follows. Shortly, in Section 1.1, we explain the justification for the quasihyperbolic metric. After that we provide the main references and some more required definitions. In Section 2 we prove our main result involving the C^1 -smoothness of the quasihyperbolic metric. As mentioned above, we also prove that under rather weak assumptions on the Banach space the metric is differentiable in a dense large set of points. Also, some results related to smoothness of the inner metrics are given in a purely metric setting. Then, in Section 3, we discuss a promising and unexpected connection between geometric function theory and functional analysis, namely using the quasihyperbolic metric to construct Banach space renormings. Finally, we give some counterexamples in Hilbertian and Euclidian spaces.

1.1. Geometric motivation of the quasihyperbolic metric. Suppose that X is a Banach space and $\Omega \subset X$ is a domain with non-empty boundary. Denote by $d(x, \partial\Omega)$ the distance of the point $x \in \Omega$ from the boundary of Ω . Then the *quasihyperbolic (QH) metric* on the domain Ω is defined by the formula

$$(1.1) \quad k_{\Omega}(x, y) = \inf_{\gamma} \int_{\gamma} \frac{\|dz\|}{d(z, \partial\Omega)},$$

where the infimum is taken over all rectifiable curves γ in Ω connecting the points x, y in Ω . If the infimum is attained for some rectifiable curve γ , this curve is called a *quasihyperbolic geodesic*.

The formula (1.1) has several important special cases. For $X = \mathbf{R}^n$, $n \geq 2$ and $\Omega = \mathbf{H}^n = \{x \in \mathbf{R}^n : x_n > 0\}$, i.e., the upper half-space, we obtain the well-known *hyperbolic metric* ρ (see [1]), also known as the *Poincaré metric*. The hyperbolic metric can also be developed in the unit disk \mathbf{B}^2 by using the formula

$$\rho_{\mathbf{B}^2}(x, y) = \inf_{\gamma} \int_{\gamma} \frac{2|dz|}{1 - |z|^2}, \quad x, y \in \mathbf{B}^2,$$

where the infimum is taken over all regular curves γ connecting x and y . This metric is conformally invariant in the following sense. Suppose that $w = f(z)$ is a conformal mapping of the unit disk onto itself. Then, by Pick's lemma, we have the identity

$$\left| \frac{dw}{dz} \right| = \frac{1 - |w|^2}{1 - |z|^2}, \quad \text{or} \quad \frac{|dw|}{1 - |w|^2} = \frac{|dz|}{1 - |z|^2}.$$

This means that, for any regular curve γ in the unit disk, we have

$$\int_{f \circ \gamma} \frac{|dw|}{1 - |w|^2} = \int_{\gamma} \frac{|dz|}{1 - |z|^2}.$$

Note that the denominators above are asymptotically equivalent to that in (1.1).

By using conformal invariance, the hyperbolic metric can be studied for other simply connected domains in the plane, and in the case of the half-plane it coincides with the metric defined by (1.1). But even in \mathbf{R}^n , the hyperbolic metric cannot be defined for domains other than half-spaces and balls for $n \geq 3$. The method based on conformal invariance does not apply to general Banach spaces.

In general, the quasihyperbolic metric is not conformally invariant, but it behaves well under conformal and even quasiconformal mappings. This fact is of particular importance in infinite dimensional spaces, where many convenient tools for studying quasiconformal mappings, such as local compactness and measure, are not

available. Besides quasiconformal mappings, the quasihyperbolic metric has recently found novel and interesting applications in other fields of geometric analysis as well.

From basic analysis of the hyperbolic disk and conformal invariance, it immediately follows that the hyperbolic geodesics originating from the point $x \in \Omega$ are always orthogonal to the surfaces of hyperbolic balls centered at x (see Figure 1). It is not obvious that a similar property holds for the quasihyperbolic metric. This very useful connection between quasihyperbolic geodesics and balls will be established in Theorem 2.10, and then exploited to obtain further results on quasihyperbolic balls. We refer to the book of Vuorinen [21] for the basic properties of the quasihyperbolic metric in \mathbf{R}^n , and the comprehensive survey article of Väisälä [19] for the basic results in Banach spaces.

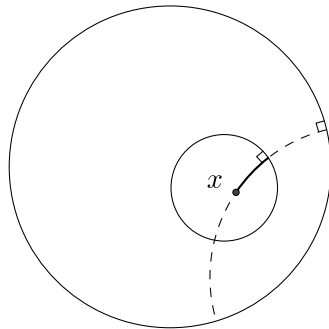


Figure 1. A geodesic radius in the hyperbolic disk.

1.2. Preliminaries. We refer to [1, 2, 3, 10, 21, 19] for background information. Many of the arguments here are written concisely, using reasoning similar to that in [16] and [17]. By a *domain* $\Omega \subset X$ of a Banach space we mean an open path-connected subset with a non-empty boundary $\partial\Omega$. We denote by $\mathbf{B}(x_0, r)$ closed balls (resp. by $\mathbf{U}(x_0, r)$ open balls) with center x_0 and radius r in a metric space and by $\mathbf{S}(x_0, r) = \partial\mathbf{B}(x_0, r)$ the corresponding spheres. The symmetric Hausdorff distance between subsets of a metric space is denoted by d_H .

We assume throughout that all Banach spaces considered have the Radon–Nikodym Property (RNP) which can be formulated as follows: Each Lipschitz path $\gamma: [0, 1] \rightarrow X$ is a.e. differentiable and the path can be recovered by Bochner integrating its derivative,

$$\gamma(t) = \gamma(0) + \int_0^t \gamma'(s) ds, \quad t \in [0, 1],$$

see [4]. Recall that the *uniform smoothness* of a Banach spaces X is defined by the following condition on $\|\cdot\|$ norm:

$$\mu_{(X, \|\cdot\|)}(\tau) = \sup\{(\|y + h\| + \|y - h\|)/2 - 1, y, h \in X, \|y\| = 1, \|h\| = \tau\},$$

$$\lim_{\tau \rightarrow 0^+} \frac{\mu_{(X, \|\cdot\|)}(\tau)}{\tau} = 0.$$

We will frequently use the fact that in bounded subdomains $D \subset \Omega$ uniformly separated from the boundary $\partial\Omega$ the quasihyperbolic metric is equivalent to the metric induced by the norm, see also the proof of Theorem 2.7.

2. On smoothness of quasihyperbolic balls in infinite-dimensional setting

Let us consider a convex domain Ω in a Banach space. It follows from the arguments provided by Väisälä and Martio in [15] that there exists a quasihyperbolic

geodesic between any two points in a convex domain of a locally weak-star compact (e.g., reflexive) space.

Let us consider paths as elements in $C([0, 1], X)$, the space of continuous functions $[0, 1] \rightarrow X$ with the sup-norm, which is a Banach space. We will consider rectifiable paths with finite quasihyperbolic length parametrized by their quasihyperbolic length, i.e., having constant speed.

We will study the following type (multi)map: $\Lambda(x, y) \mapsto \{\gamma\}$ which assigns to each endpoints all the corresponding quasihyperbolic geodesics.

Proposition 2.1. *In a reflexive, strictly convex Banach space with convex domain Ω the mapping Λ is well-defined and single-valued, $\Omega \times \Omega \rightarrow C([0, 1], X)$.*

Proof. Indeed, under the assumption the geodesics exist and are unique, see [16]. \square

Lemma 2.2. *The path length functional*

$$\ell_k \gamma = \int_{\gamma} \frac{\|\gamma'(t)\|}{d(\gamma(t), \partial\Omega)} dt$$

is convex.

Proof. Take the point-wise weighted average of two rectifiable paths γ_0 and γ_1 , $\gamma_s(t) := (1 - s)\gamma_0(t) + s\gamma_1(t)$, $s \in [0, 1]$. Then

$$\ell_k \gamma_s \leq (1 - s)\ell_k \gamma_0 + s\ell_k \gamma_1.$$

This follows from the inequality

$$(2.3) \quad \frac{\|((1 - s)\gamma_0 + s\gamma_1)'\|}{d((1 - s)\gamma_0 + s\gamma_1, \partial\Omega)} \leq \frac{(1 - s)\|\gamma_0'\|}{d(\gamma_0, \partial\Omega)} + \frac{s\|\gamma_1'\|}{d(\gamma_1, \partial\Omega)},$$

see [16, (4.6)]. \square

Suppose next that X is an *Asplund space*. This is a weaker condition than reflexivity and is dual to the RNP condition of a Banach space. The Asplund property has the following equivalent formulation: Each continuous convex function $f: X \rightarrow \mathbf{R}$ is Fréchet differentiable in a generic set, i.e., a dense G_δ subset.

Theorem 2.4. *Suppose that X is an Asplund space and $\Omega \subset X$ is a convex domain. Then the quasihyperbolic metric $k(x, y)$ is Fréchet smooth in a generic subset of $\Omega \times \Omega$. If we fix one coordinate, $k_{x_0}(y) := k(x_0, y)$ is Fréchet smooth in a generic subset of Ω .*

Proof. In the case with a strictly convex reflexive space the function

$$k(x, y) = \ell_k \Lambda(x, y)$$

is convex by the above Proposition 2.1 and Lemma 2.2. Indeed, if γ_0 (resp. γ_1) is a geodesic connecting x_0 to y_0 (resp. x_1 to y_1), then

$$\begin{aligned} k((1 - s)x_0 + sx_1, (1 - s)y_0 + sy_1) &\leq \ell_k(\gamma_s) \\ &\leq (1 - s)\ell_k(\gamma_0) + s\ell_k(\gamma_1) = (1 - s)k(x_0, y_0) + sk(x_1, y_1). \end{aligned}$$

It is easy to see that k is Lipschitz on domains uniformly separated from the boundary $\partial\Omega$. Thus Asplund property applies.

In the non-strictly convex, non-reflexive case we still have the convexity of k . The statement of the theorem can then be seen for example by approximation with quasigeodesics in place of $\Lambda(x, y)$.

The latter part of the statement is seen in a similar fashion. □

Remark 2.5. The above statement also holds if Asplund condition is replaced by separability and Fréchet differentiability by Gâteaux differentiability. Indeed, it is known that separable Banach spaces are weak Asplund spaces (where the formulation runs analogously where Gâteaux differentiability appears in place of Fréchet differentiability).

Theorem 2.6. *If Ω is convex and the norm of X is uniformly convex, then the mapping $(\Lambda)’: \Omega^2 \rightarrow L^1(X)$, $(x, y) \mapsto \gamma’$, is $\|\cdot\|_{X \oplus X} \cdot \|\cdot\|_{L^1(X)}$ -continuous.*

Sketch of proof. Let $x_n \rightarrow x$, $y_n \rightarrow y$ in norm in Ω . Then the convergences hold in the quasihyperbolic metric as well by the local bi-Lipschitz equivalence of the metrics.

According to the above observations there are unique geodesics γ_n and γ be geodesics connecting x_n to y_n and x to y , respectively. Assume further that these are parameterized by constant quasihyperbolic path length growth. Analyze the quasihyperbolic length of the averages $\frac{1}{2}(\gamma + \gamma_n)$. It turns out by using the modulus of convexity on (2.3) that $\|\gamma’ - \gamma_n’\| \rightarrow 0$ in measure as $n \rightarrow \infty$. Indeed, otherwise $\liminf_{n \rightarrow \infty} \ell_k(\frac{1}{2}(\gamma + \gamma_n)) < \ell_k(\gamma)$ stating that

$$\liminf_{n \rightarrow \infty} k\left(\frac{x + x_n}{2}, \frac{y + y_n}{2}\right) < k(x, y),$$

which is impossible. Since these derivatives are essentially bounded according to the parametrization of the paths, we obtain

$$\int_0^1 \|(\gamma - \gamma_n)’(t)\| dt \rightarrow 0 \text{ as } n \rightarrow \infty. \quad \square$$

Theorem 2.7. *Let X be a uniformly smooth Banach space and let $\Omega \subset X$ be a convex domain. Then the quasihyperbolic balls are smooth in the sense that $k(x_0, \cdot)$, $x_0 \in \Omega$, is continuously Fréchet differentiable away from x_0 .*

Proof. Let B be a quasihyperbolic ball as above. Observe that there is a radius $\epsilon > 0$ such that $\|\cdot\|$ and $k_0(\cdot) := k(x_0, \cdot)$ are bi-Lipschitz equivalent in

$$(\partial B)^\epsilon = \{x \in \Omega : d(x, \partial B) < \epsilon\}.$$

This is due to the fact that on B^ϵ the weight $\frac{1}{d(x, \partial \Omega)}$ is bounded. This in turn is based on the observation that

$$\int_0^T \frac{dt}{L(t)} = \infty,$$

for any 1-Lipschitz mapping L with $L(t) \rightarrow 0$ as $t \nearrow T$. Here T represents the norm length of a rectifiable path and L represents $d(\gamma(t), \partial \Omega)$.

Let us verify that k_0 is indeed Fréchet differentiable away from the origin. Towards this, let $\gamma : [0, \ell] \rightarrow \Omega$ be a quasihyperbolic geodesic joining two points $\gamma(0) = x_0, \gamma(\ell) \in B$ and parameterized by the *norm* path length. By thinking of B as a closure of incremental sequence of quasihyperbolic balls it is easy to see that γ is fully contained in B .

We wish to show that

$$(2.8) \quad \frac{1}{\|h\|} (k(\gamma(0), \gamma(\ell) + h) + k(\gamma(0), \gamma(\ell) - h) - 2k(\gamma(0), \gamma(\ell))) \rightarrow 0$$

as $\|h\| \rightarrow 0$ uniformly, not depending on the particular endpoints or length ℓ . However, we will assume that ℓ is uniformly bounded away from zero.

Fix h such that $\gamma(\ell) \pm h \in \Omega$. Write $t = \sqrt{\|h\|}$. Define new paths γ_+ and γ_- as follows: on the segment $[0, \ell - t]$ they coincide with γ and

$$\gamma_{\pm}(\ell - t + s) = \gamma(\ell - t + s) \pm s^2 \frac{h}{\|h\|} \quad \text{for } 0 \leq s \leq t.$$

Note that this definition is not sensible if ℓ is allowed to have values smaller than t . The asymptotics of (2.8) can be estimated by studying the sum of the lengths of γ_{\pm} . We are only required to study the behavior at parameter values on $[\ell - t, \ell]$.

Note that we may write $\mu_{\|\cdot\|}(\tau) = \tau\epsilon(\tau)$ where $\epsilon(\tau) \searrow 0$ as $\tau \rightarrow 0$. Write

$$d^* = \sup_{y \in B^\epsilon} \left| \frac{d}{dt} \frac{1}{t} \Big|_{t=d(y, \partial\Omega)} \right|.$$

Recall that $\|\gamma'\| = 1$ a.e., by the parameterization. Note that

$$\|(\gamma_{\pm}(\ell - t + s) - \gamma(\ell - t + s))'\| = \left\| \pm \frac{d}{ds} s^2 \frac{h}{\|h\|} \right\| = 2s.$$

Thus by using the definition of the modulus of smoothness we obtain that

$$\sum_{\pm} \|\gamma'_{\pm}(\ell - t + s)\| \leq 2(1 + \mu_{\|\cdot\|}(2s)).$$

Also note that

$$\frac{1}{d(\gamma_{\pm}(\ell - t + s), \partial\Omega)} \leq \frac{1}{d(\gamma(\ell - t + s), \partial\Omega)} + s^2 d^*$$

by the mean value principle. We obtain that

$$\begin{aligned} & k(\gamma(0), \gamma(\ell) + h) + k(\gamma(0), \gamma(\ell) - h) - 2k(\gamma(0), \gamma(\ell)) \\ & \leq \ell_{QH}(\gamma_+) + \ell_{QH}(\gamma_-) - 2\ell_{QH}(\gamma) = \int_{s=0}^t \frac{\|\gamma'_+(\ell - t + s)\|}{d(\gamma_+(\ell - t + s), \partial\Omega)} ds \\ & \quad + \int_{s=0}^t \frac{\|\gamma'_-(\ell - t + s)\|}{d(\gamma_-(\ell - t + s), \partial\Omega)} ds - 2 \int_0^t \frac{ds}{d(\gamma(\ell - t + s), \partial\Omega)} \\ & \leq \int_{s=0}^t 2(1 + \mu_{\|\cdot\|}(2s)) \left(\frac{1}{d(\gamma(\ell - t + s), \partial\Omega)} + s^2 d^* \right) ds - 2 \int_0^t \frac{ds}{d(\gamma(\ell - t + s), \partial\Omega)}. \end{aligned}$$

We claim that the bottom value converges to 0 faster than $t^2 \rightarrow 0$. Since $s^2 \leq t^2 \rightarrow 0$ we are only required to investigate the term involving $\mu_{\|\cdot\|}$.

Note that since $y \mapsto \frac{1}{d(y, \partial\Omega)}$ is Lipschitz on B (see the proof of Theorem 2.7), there is small enough T (or $\|h\|$) such that

$$1/d(\gamma(\ell - t + s), \partial\Omega) \leq 2/d(\gamma(\ell), \partial\Omega) \quad \text{for } t \leq T.$$

Let us estimate

$$\begin{aligned} & \frac{1}{t^2} \int_0^t 2\mu_{\|\cdot\|}(2s) \left(\frac{1}{d(\gamma(\ell - t + s), \partial\Omega)} + s^2 d^* \right) ds \\ & \leq \frac{1}{t^2} \int_0^t 4s\epsilon(2s) \left(\frac{2}{d(\gamma(\ell), \partial\Omega)} + s^2 d^* \right) ds \leq \frac{1}{t^2} \Big|_{s=0}^t \epsilon(2t) \left(\frac{4s^2}{d(\gamma(\ell), \partial\Omega)} + s^4 d^* \right) \\ & = \epsilon(2t) \left(\frac{4}{d(\gamma(\ell), \partial\Omega)} + t^2 d^* \right) \rightarrow 0, \quad t \rightarrow 0. \end{aligned}$$

In fact, we observe by going through the calculations that if $p, r \in [1, 2)$, $r \leq (p + 1)/2$, $r < 3/2$ and $\mu_{\|\cdot\|}(\tau) = \tau^p \epsilon(\tau)$ where $\epsilon(\tau) \searrow 0$ as $\tau \rightarrow 0$, then we have

$$\frac{1}{\|h\|^r} (k(x_0, x + h) + k(x_0, x - h) - 2k(x_0, x)) \rightarrow 0$$

as $\|h\| \rightarrow 0$ uniformly in any annulus whose distance to x_0 and $\partial\Omega$ is strictly positive. In particular, for $p = r = 1$ this states that uniform smoothness of the norm implies Fréchet differentiability of the function $k_0(\cdot)$ in open annuli $(\partial B)^\epsilon$ as above, since the convergence is uniform in $\|h\|$. In fact, since the convergence is uniform both in x and $\|h\|$ we have uniform Fréchet differentiability, see [3, pp. 242, 289]. This means that taking the Fréchet derivative $x \mapsto (k_0)'(x)$ is a uniformly continuous map $U \rightarrow X^*$ for any open convex $U \subset \Omega$ uniformly separated from the x_0 and $\partial\Omega$. \square

Remark 2.9. The question of smoothness of quasihyperbolic balls has been studied at least since 1979, when it was asked by Vuorinen from Gehring. In an unpublished note [6], Gehring proposed that quasihyperbolic balls $\mathbf{B}_k(0, r)$, $r > 0$, in the two-dimensional domain $D = \{z = (z_1, z_2) \in \mathbf{R}^2 : -1 < z_2 < 1\}$ are not smooth. The above result shows that this is not a valid counterexample. See also [22].

If the domain is symmetric and centered at the origin and the ball is centered as well, then it is ‘uniformly smooth’ in the sense that it induces a uniformly smooth norm by the Minkowski functional. This condition is considerably stronger than mere C^1 -smoothness.

The following result can be viewed as a kind of metric orthogonality between the quasihyperbolic spheres and the quasihyperbolic geodesics emanated from the quasihyperbolic center of these spheres.

Theorem 2.10. *Let Ω be a domain as above and $x_0, x \in \Omega$. Suppose that $\gamma: [0, 1] \rightarrow \Omega$ is a quasihyperbolic geodesic and $r = k(x_0, x)$, $\gamma(0) = x_0$, $\gamma(1) = x$. Then*

$$\lim_{t \rightarrow 1^-} \frac{d_{\|\cdot\|}(\gamma(t), \mathbf{S}_k(x_0, r))}{\|\gamma(t) - \gamma(1)\|} = 1.$$

In the above limit one may also replace $\|x - y\|$ by $k(x, y)$.

The above statement holds similarly in a path-connected geodesic metric space (X, d) with a continuous weight and such that $\frac{\ell_d(\gamma|_{[t,1]})}{d(\gamma(t), \gamma(1))} \rightarrow 1$ as $t \rightarrow 1^-$ for any geodesic $\gamma: [0, 1] \rightarrow X$. Surprisingly, the above orthogonality is mainly setting-free, it only depends on the conformality of the inner metric.

Proof. We will prove the case with a general strictly positive continuous weight function w in place of $1/d(x, \partial\Omega)$ and a domain Ω of a Banach space. We first observe that

$$\limsup_{t \rightarrow 1^-} \frac{d_{\|\cdot\|}(\gamma(t), \mathbf{S}_w(x_0, r))}{\|\gamma(t) - \gamma(1)\|} \leq 1.$$

Thus it suffices to check that

$$\liminf_{t \rightarrow 1^-} \frac{d_{\|\cdot\|}(\gamma(t), \mathbf{S}_w(x_0, r))}{\|\gamma(t) - \gamma(1)\|} \geq 1.$$

Let

$$\underline{w}_t = \inf\{w(x) : \|x - \gamma(1)\| \leq 3\|\gamma(t) - \gamma(1)\|\}$$

and

$$\bar{w}_t = \sup\{w(x) : \|x - \gamma(1)\| \leq 3\|\gamma(t) - \gamma(1)\|\}.$$

Note that

$$\lim_{t \rightarrow 1^-} \underline{w}_t = \lim_{t \rightarrow 1^-} \overline{w}_t = w(\gamma(1)).$$

Choose $t < 1$ such that

$$\frac{w_s}{\overline{w}_s} > \frac{1}{2}, \quad s \in (t, 1)$$

and there is $r > 0$ satisfying

$$\gamma(s) \in B_{\|\cdot\|}(\gamma(1), r) \subset B_{\|\cdot\|}(\gamma(1), 3r) \subset \Omega, \quad s \in (t, 1).$$

Assume that λ is a rectifiable path starting from $\gamma(t)$ and ending in $\gamma(1)$. First suppose that λ is not included in the following set:

$$(2.11) \quad D = \{x \in \Omega: \|x - \gamma(1)\| \leq 3\|\gamma(t) - \gamma(1)\|\}.$$

This means that

$$\ell_w(\lambda) \geq 3\underline{w}_t\|\gamma(t) - \gamma(1)\| > 2\underline{w}_t\|\gamma(t) - \gamma(1)\| > \overline{w}_t\|\gamma(t) - \gamma(1)\| \geq d_w(\gamma(t), \mathbf{S}_w(x_0, r)).$$

It follows that $\ell_w(\lambda) > \frac{3}{2}\ell_w(\gamma|_{[t,1]})$. Therefore in studying w -short paths λ between $\gamma(t)$ and the set $\mathbf{S}_w(x_0, r)$ we may restrict to the case where the paths are included in the above set D in (2.11).

Fix $y_t \in \mathbf{S}_w(x_0, r) \cap D$. Suppose without loss of generality that $\lambda^{(t)}$ is a w -geodesic between $\gamma(t)$ and y_t . Indeed, if there does not exist a geodesic between the given points then we may pass on to an approximating sequence of paths λ_n and the rest of the argument does not change considerably.

Note that

$$\ell_{\|\cdot\|}(\gamma|_{[t,1]})\underline{w}_t \leq \ell_{\|\cdot\|}(\lambda^{(t)})\overline{w}_t.$$

Thus

$$\frac{\underline{w}_t}{\overline{w}_t} \leq \frac{\ell_{\|\cdot\|}(\lambda^{(t)})}{\ell_{\|\cdot\|}(\gamma|_{[t,1]})}$$

where the left hand side tends to 1 as $t \rightarrow 1$.

To estimate the right hand side we observe similarly as above that

$$\|\gamma(t) - \gamma(1)\| \leq \ell_{\|\cdot\|}(\gamma|_{[t,1]}) \leq \frac{\overline{w}_t}{\underline{w}_t} \|\gamma(t) - \gamma(1)\|$$

and an analogous statement holds for $\lambda^{(t)}$ also. Thus we obtain

$$1 \leq \liminf_{t \rightarrow 1^-} \frac{\ell_{\|\cdot\|}(\lambda^{(t)})}{\ell_{\|\cdot\|}(\gamma|_{[t,1]})} = \liminf_{t \rightarrow 1^-} \frac{\|\gamma(t) - y_t\|}{\|\gamma(t) - \gamma(1)\|}.$$

This yields the claim since the selections of the points y_t were arbitrary. □

The following result says that a quasihyperbolic ball does not have cusps.

Theorem 2.12. *For a proper subdomain Ω of X , radius $r > 0$ and $y \in \partial\mathbf{B}_k(x, r)$, let γ be a quasihyperbolic geodesic joining x and y . For $z \in \gamma$ we have*

$$\mathbf{B}_{\|\cdot\|} \left(z, \frac{|z - y|}{1 + u} \right) \subset \mathbf{B}_k(x, r),$$

where $u = |z - y|/d(z, \partial\Omega)$.

The proof follows verbatim the proof of Theorem 2.8 in [11] and is reproduced here for the sake of convenience.

Proof. By the choice of z we have

$$r = k(x, y) = k(x, z) + k(z, y)$$

and by the triangle inequality for $w \in \mathbf{B}_k(z, k(z, y))$ we have

$$k(x, w) \leq k(x, z) + k(z, w) < r.$$

Now

$$\mathbf{B}_k(z, k(z, y)) \subset \mathbf{B}_k(x, r).$$

Next we will apply some known estimates involving the quasihyperbolic metric. These have been proven in the Euclidean setting, see [21], but since the proofs do not depend on the particular choice of the norm, we may use them in Ω as well.

We have

$$\mathbf{B}_{\|\cdot\|}(z, (1 - e^{-k_G(z,y)}) d(z, \partial\Omega)) \subset \mathbf{B}_k(z, k(z, y)),$$

and thus

$$\mathbf{B}_{\|\cdot\|}(z, (1 - e^{-k(z,y)}) d(z, \partial\Omega)) \subset \mathbf{B}_k(x, r).$$

It holds that $k(z, y) \geq \log(1 + |z - y|/d(z, \partial\Omega))$, and therefore

$$(1 - e^{-k(z,y)}) d(z, \partial\Omega) \geq \left(1 - \frac{d(z, \partial\Omega)}{d(z, \partial\Omega) + |z - y|}\right) d(z, \partial\Omega) = \frac{|z - y|}{1 + u}$$

for $u = |z - y|/d(z, \partial\Omega)$. Now

$$\mathbf{B}_{\|\cdot\|}\left(z, \frac{|z - y|}{1 + u}\right) \subset \mathbf{B}_{\|\cdot\|}(z, (1 - e^{-k(z,y)}) d(z, \partial\Omega)),$$

and the claim follows. □

3. Quasihyperbolic metric as a renorming technique

Proposition 3.1. *Let $\Omega \subset X$ be domain which is a convex, bounded and symmetric (invariant under multiplication by -1). Then any quasihyperbolic ball $B = \mathbf{B}_k(0, r)$, $r > 0$, defines an equivalent norm in X by the Minkowski functional*

$$M(x) := \inf\{\lambda > 0: x \in \lambda B\}.$$

Proof. It is easy to see that under the assumptions each centered open quasihyperbolic ball B is a norm-open, bounded and symmetric subset. Moreover, it follows from the considerations in [16] that B is convex. It is well-known that in such a case the Minkowski functional $M(x)$ defines an equivalent norm in X . □

The smoothness properties of this equivalent norm encode essentially all the relevant smoothness information involving the quasihyperbolic ball. Thus, one may also apply the well-matured Banach space theory to approach the problem of smoothness of the balls. Note that the above norm is different for different radii of the quasihyperbolic ball.

One of the problems in the theory of renormings of Banach spaces (see [2]) is the approximation of the norm of the space by other norms uniformly on bounded sets such that the approximating norm satisfy some nice properties. This task, of course, is sensible only if the space admits an equivalent norm with the given properties in the first place. In most cases the non-separability of the Banach space somewhat complicates the constructions of the nice equivalent norms and in some cases it is not clear how the constructions extend from the separable to the non-separable setting (see, e.g., [9]).

Above we showed how to induce a norm by a Minkowski functional using a centered quasihyperbolic balls on a convex, bounded and symmetric domain. Thus the domain Ω is essentially an open unit ball given by an equivalent norm $\|\cdot\|$, i.e., $\Omega = \mathbf{U}_{\|\cdot\|}$. However, it is easy to see that if we let the quasihyperbolic radius

tend to infinity, then the corresponding quasihyperbolic sphere $\partial\mathbf{B}_k(0, r)$ converges to the sphere $\mathbf{S}_{|||\cdot|||}$ in the sense of symmetric Hausdorff distance (taken with respect to any of the equivalent metrics), see the proof of Theorem 2.7. This means that the norms $\|x\|_{(r)} := M_{\mathbf{B}_k(0,r)}(x)$ induced by the quasihyperbolic balls approximate $|||\cdot|||$ uniformly on bounded sets.

This approach has two convenient features. First, as we have seen here, the approximation part comes for free, only thing that is left to do is to analyze the quasihyperbolic balls regarding the favorable property. Secondly, the analysis of the quasihyperbolic balls is usually not sensitive to whether or not the space is separable. Also, the way the quasihyperbolic inner metric is defined appears to have a mildly smoothening effect on the resulting norms, per se.

Theorem 3.2. *Suppose that $(X, \|\cdot\|)$ is a uniformly smooth Banach space. Then each equivalent norm can be approximated uniformly on bounded sets by uniformly smooth norms induced by the quasihyperbolic balls, similarly as in Proposition 3.1. Moreover, if the modulus of smoothness of the norm $\|\cdot\|$ has power type $1 < p \leq 2$, then the approximating norms have all the power types $< (p + 1)/2$.*

Sketch of proof. Let $B_n = \mathbf{B}_k(0, n)$. By the proof of Theorem 2.7 we know that k is continuously Fréchet differentiable on domains $(\partial B_n)^\varepsilon$ with suitable $\varepsilon > 0$.

Now, since ∂B_n is the level set of a continuously Fréchet differentiable function, a standard argument employing the Implicit Function Theorem gives that the norm $|||\cdot|||_n := M_{B_n}(\cdot)$ is also continuously Fréchet differentiable, see [2, pp. 163–168]. In fact, in estimating from above the modulus of smoothness of the $M_{B_n}(\cdot)$ norms, we may restrict by geometric considerations to a version of the modulus as follows:

$$\mu_n(\tau) = \sup \left\{ \frac{|||y+h|||_n + |||y-h|||_n}{2} - 1 : \right. \\ \left. |||y+h|||_n, |||y-h|||_n \geq |||y|||_n = 1, \|h\| = \tau \right\}.$$

By the triangle inequality we obtain that

$$|||y \pm h|||_n - 1 \leq |||y \pm h|||_1 - |||y|||_1 \leq C d_{\|\cdot\|}(y \pm h, \partial B_n), \quad y \in \partial B_n$$

where C is the isomorphism constant involving the equivalent norms $\|\cdot\|$ and $|||\cdot|||_1$.

Suppose that $|||y \pm h|||_n \geq 1$. Then

$$k_0(y \pm h) \geq k_0(y) + d_{\|\cdot\|}(y \pm h, \partial B_n) \inf\{1/d(x, \partial\Omega) : x \in \partial B_n\}$$

by the definition of the k metric. Thus, for large n the above infimum becomes larger than C , so that for large enough n we have

$$\sup \left\{ \frac{|||y+h|||_n + |||y-h|||_n}{2} - 1 : |||y+h|||_n, |||y-h|||_n \geq |||y|||_n = 1, \|h\| = \tau \right\} \\ \leq \sup \left\{ \frac{k_0(y+h) + k_0(y-h)}{2} - k_0(y) : k_0(y+h), k_0(y-h) \geq k_0(y), \|h\| = \tau \right\}$$

holds. The latter quantity is controlled in the proof of Theorem 2.7. □

Remark 3.3. The proof of the following remark is based on Banach space ultrapowers and is omitted here. Suppose that X is a uniformly convex Banach space, $\Omega \subset X$ is a symmetric convex domain and $B = B_k(0, r)$ for some $r > 0$. Then the equivalent norm $|||\cdot||| = M_B(\cdot)$ on X is uniformly convex.

Moreover, any equivalent norm on X can be approximated uniformly on bounded sets by uniformly convex norms arising from such quasihyperbolic balls B .

Proposition 3.4. *Suppose that X is a strictly convex Banach space with the RNP. Then each equivalent norm can be approximated uniformly on bounded sets by strictly convex norms induced by the quasihyperbolic balls, similarly as above.*

Proof. The argument is based on the fact that quasihyperbolic balls in a convex domain of a strictly convex Banach space with the RNP are strictly convex as well, see [16]. Note that it is not essential here whether $\bar{\Omega}$ is strictly convex or not. \square

We do not know if quasihyperbolic balls in symmetric convex domains of reflexive LUR Banach spaces and centered at the origin induce LUR norms via the Minkowski functional.

4. Final remarks: Non-geodesic domains

There exists examples of domains in Hilbert spaces, which are not geodesic with respect to the quasihyperbolic metric. For more details see [18, Example 2.9] and [19, Remark 3.5]. However, in these examples the complement of the domain is uncountable. We give an example of a domain that is not geodesic with respect to the quasihyperbolic metric and the complement of the domain is countable.

Example 4.1. Let

$$G = \ell^2 \setminus \left(\{0\} \cup \left\{ \pm\sqrt{2} \left(1 - \frac{1}{i} \right) e_i \right\}_{i=2}^{\infty} \right).$$

There does not exist a quasihyperbolic geodesic from $-e_1$ to e_1 in G .

Proof. In $G' = \ell^2 \setminus \{0\}$ the geodesics $-e_1 \curvearrowright e_1$ are half circles with center at 0. Since $G' \subset G$ we have

$$k_G(-e_1, e_1) \geq k_{G'}(-e_1, e_1) = \pi.$$

Let γ be a curve joining $-e_1$ to e_1 . If γ is not a half circle, then

$$k_G(\gamma) \geq k_{G'}(\gamma) > \pi.$$

If γ is a half circle, then for some n we have $\min\{d(e_n, \gamma), d(-e_n, \gamma)\} < 1$ implying $k_G(-\gamma) > \pi$.

Let us consider γ_n to be a half circle with center at origin, end points $-e_1$ and e_1 such that for each $x = (x_1, x_2, \dots) \in \gamma_n$ we have

$$x_1 \in [-1, 1], \quad 0 = x_2 = \dots = x_{n-1} = x_{n+2} = \dots, \quad x_n = x_{n+1}$$

for some $n \geq 2$. By construction of G we have $\ell_k(\gamma_n) > \ell_k(\gamma_{n+1}) > \pi$ and $\lim_{n \rightarrow \infty} \ell_k(\gamma_n) = \pi$. Thus, there does not exist a quasihyperbolic geodesic. \square

5. On uniqueness of geodesics in finite-dimensional domains

Finally, we take this opportunity to address some related finite-dimensional questions involving the quasihyperbolic metric that arose during our research.

In the upper half-plane the quasihyperbolic geodesics agree with the hyperbolic geodesics and are thus unique. However, if a plane domain is not simply connected the quasihyperbolic geodesics need not be unique. The following results shows that for any $n \geq 3$ there exists a domain and at least two geodesics with exactly n common points.

Lemma 5.1. For each $n = 2, 3, \dots$ there exists a domain $G \subsetneq \mathbf{R}^2$, points $x, y \in G$ and quasihyperbolic geodesics $\gamma_1: x \curvearrowright y$ and $\gamma_2: x \curvearrowright y$ such that $\#(\gamma_1 \cap \gamma_2) = n$.

Proof. In the case of $n = 2$ we can choose $G = \mathbf{R}^2 \setminus \{0\}$, $x = -e_1$ and $y = e_1$. Now there exists exactly two geodesics joining x and y , which are half circles, and we choose them to be γ_1 and γ_2 . We obtain $\#(\gamma_1 \cap \gamma_2) = 2$ and the assertion follows.

We assume that $n \geq 3$. Let us first construct the domain G . We define rectangular $R_n = \{z = (z_1, z_2) \in \mathbf{R}^2: z_1 \in (-1, (n - 2)\sqrt{3} + 1), z_2 \in (-1, 1)\}$ and point set $P_n = \{0, \sqrt{3}, \dots, (n - 2)\sqrt{3}\}$. Next we define the set

$$L_n = \left\{ z \in \mathbf{R}^2: z_2 \leq -\frac{1}{2}, z_2 \geq \frac{1}{2}, z_1 \in \left\{ \frac{\sqrt{3}}{2}, \sqrt{3} + \frac{\sqrt{3}}{2}, \dots, (n - 3)\sqrt{3} + \frac{\sqrt{3}}{2} \right\} \right\}.$$

We define

$$G_n = R_n \setminus (P_n \cup L_n).$$

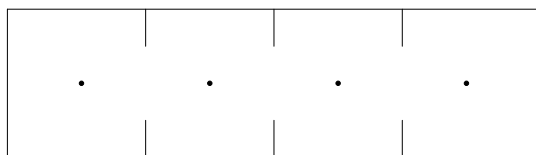


Figure 2. The domain $G_5 = R_5 \setminus (P_5 \cup L_5)$.

We choose $x = -\frac{1}{2}e_1$ and $y = ((n - 2)\sqrt{3} + \frac{1}{2})e_1$. Finally, we find the geodesics γ_1 and γ_2 . Let γ_1 be the geodesic, which consists of circular arcs and is contained in the closed upper half-plane $\{z = (z_1, z_2) \in \mathbf{R}^2: z_1 \geq 0, z_2 \in \mathbf{R}_n\}$, see Figure 3. Then

$$\gamma_1 \cap \{z = (z_1, z_2): z_1 = 0\} = \left\{ 0, \frac{\sqrt{3}}{2}e_1, \frac{3\sqrt{3}}{2}e_1, \dots, \frac{(2n-5)\sqrt{3}}{2}e_1, \left((n - 2)\sqrt{3} + \frac{1}{2} \right) e_1 \right\}.$$



Figure 3. Geodesic γ_1 in the proof of Lemma 5.1.

Let γ_2 be the reflection of γ_1 across the x_1 -axis. Now

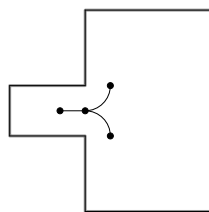
$$\gamma_1 \cap \gamma_2 = \left\{ 0, \frac{\sqrt{3}}{2}e_1, \frac{3\sqrt{3}}{2}e_1, \dots, \frac{(2n-5)\sqrt{3}}{2}e_1, \left((n - 2)\sqrt{3} + \frac{1}{2} \right) e_1 \right\}$$

implying $\#(\gamma_1 \cap \gamma_2) = n$ and the assertion follows. □

Remark 5.2. Note that Lemma 5.1 is true for all geodesics γ_1 and γ_2 joining the points x and y . There are 2^{n-1} of such geodesics.

Next we give an example of a strictly starlike domain, which contains arbitrarily short quasihyperbolic geodesics, which cannot be uniquely prolonged.

Example 5.3. Let us consider the polygon $P \subset \mathbf{R}^2$ with vertices at $(-4, 1)$, $(-1, 1)$, $(-1, 4)$, $(4, 4)$, $(4, -4)$, $(-1, -4)$, $(-1, -1)$ and $(-4, -1)$. Let first $x = (-2, 0)$, $y = (-1, 0)$, $z_1 = (0, 1)$ and $z_2 = (0, -1)$. Now the quasihyperbolic geodesic $x \curvearrowright y$ is the Euclidean line segment $[x, y]$ and geodesics $x \curvearrowright z_1$ and $x \curvearrowright z_2$ pass through point y and contain the geodesic $x \curvearrowright y$. Thus the geodesic $x \curvearrowright y$ cannot be uniquely prolonged.

Figure 4. Polygon P and geodesics in Example 5.3.

Let then $x = (-t - 1, 0)$ for some $t \in (0, 1)$. By simple computation we notice that $k_P(x, y) = t$ and similarly as above the geodesic $x \curvearrowright y$ cannot be uniquely prolonged.

Proposition 5.4. *There exists a star-like domain $\Omega \subset \mathbf{R}^n$, $n \geq 3$, such that not all the quasihyperbolic geodesics are unique. Moreover, this domain can be chosen in such a way that the function $x \mapsto 1/d(x, \partial\Omega)$ does not have any local maxima.*

Proof. Consider the following domain

$$\Omega = \left\{ (x_i) \in \mathbf{R}^n : 0 < \sqrt{\sum_{i < n} |x_i|^2} < 1, x_n \geq \frac{1}{2} \right\} \cup \{(x_i) \in B(1/2, 1) : x_n < 1/2\}.$$

Now the geodesics from $x = x_1/2 + x_n$ to $y = -x_1/2 + x_n$ are not unique. Clearly, the function $x \mapsto 1/d(x, \partial\Omega)$ does not have any local maxima, and its global maximum is $1/2$. \square

Acknowledgments. The third named author has been financially supported by Väisälä foundation's and the Finnish Cultural Foundation's research grants and Academy of Finland Project # 268009.

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